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Spong is the 2005 President of the IEEE Control Systems Society and past Editor-in-Chief of the IEEE Transactions on Control Systems Technology. Seth Hutchinson is currently a Professor at the University of Illinois in Urbana-Champaign, and a senior editor of the IEEE Transactions on Robotics and Automation.

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Theory and mathematics for robotics, you need to understand static and dynamic mechanics very well

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Executive Committee, IEEE Control Systems Society, 1997-2002 and 2004-2007 Nominating Committee, IEEE Control Systems Society, 2006-2008 General Chair, 2010 IEEE Conference on Decision and Control

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Robot Modeling and Control introduces the fundamentals of robot modeling and control and provides background material on terminology, linear algebra, dynamical systems and stability theory, followed by detailed coverage of forward and in-verse kinematics, Jacobians, Lagrangian dynamics, motion planning, robust and adaptive motion and force control, and com-puter vision.

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